

Injecting (Micro)Intelligence in the IoT: Logic-based Approaches for (M)MAS

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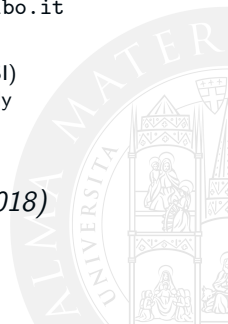
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Invited Talk @ *International Workshop
on Massively Multi-Agent Systems (MMAS 2018)*
Stockholm, Sweden, 14 July 2018



Abstract

Pervasiveness of ICT resources along with the promise of ubiquitous intelligence is pushing hard both our *demand* and our *fears* of AI: demand mandates for the ability to inject (*micro*)*intelligence* ubiquitously, fears compel the behaviour of intelligent systems to be *observable*, *explainable*, and *accountable*. Whereas the first wave of the new “AI Era” was mostly heralded by non-symbolic approaches, features like explainability are better provided by symbolic techniques. In this talk we focus on logic-based approaches, and discuss their potential in pervasive scenarios like the IoT and open (M)MAS along with our latest results in the field.

Or, What are We Going to Talk About?

Some basic questions

- how are we going to **shape the world** around our multitude of agents?
- how are we going to **spread knowledge** and **intelligence** for agents (and humans) to make the best use of it?

Some less basic questions

- nowadays, the AI pendulum is oscillating towards *non-symbolic* approaches: do we really think it is going to *stop* there?
- what have *symbolic* techniques to say **before we hit the next AI wall**?

Disclaimer

These slides are mostly for after-talk readers

- not really made for attendants following the presentation
 - they are *waaaaay* too many for the presentation
- but, they typically work quite well *after* the presentation
 - since basically no one takes notes during the presentation, nowadays
- you can find them
 - on SlideShare
 - on our APICe server
 - or, just ask us
- a *pre-emptive sorry* to those who hate that sort of presentation!



- 1 Scenarios
 - IoT & (M)MAS
 - Distributed Knowledge & Intelligence
- 2 Machine Intelligence
 - Micro-intelligence
 - (Socio-)Technical Requirements
 - Symbolic vs. Non-symbolic
- 3 The LP Road to Micro-intelligence
 - LP for Intelligent Systems
 - LP for the IoT



Next in Line...

- 1 Scenarios
- 2 Machine Intelligence
- 3 The LP Road to Micro-intelligence



Focus on. . .

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ICT & Human Environment

Changing human environment

- human environment is more and more affected and even shaped by the increasing availability of ICT resources
- in particular within the constantly-growing urban areas all over the world
- the ubiquitous availability of personal devices, sensors networks, actuators, and computational resources in general, is affecting human environment
- in particular, changing urban environments into wannabe-*smart environments* on a massively-large scale

Internet of Things (IoT)

Computing & connecting myriad of devices

- the Internet of Things (IoT) [Atzori et al., 2010] is designed to connect millions of (diverse) things (objects, devices) altogether
- things that *compute* and *connect* with each other
- in a **smart** way [Xiang and Li, 2012]



IoT & (M)MAS

IoT as a (M)MAS scenario

- (massive) multi-agent systems ((M)MAS) have been already recognised as the most promising way for developing applications for the IoT and cyber-physical systems (CPS)
 - since agents support decentralised, loosely-coupled and highly dynamic, heterogeneous and open systems, where components cooperate opportunistically [Savaglio et al., 2018]
- IoT and pervasive systems can be seen as (M)MAS
- monitoring and controlling our environments
 - where MAS abstractions, techniques, and methods cope with the complexity of the application scenarios



Intelligence & IoT

Agents & intelligence for IoT

- devices in IoT systems have to be massively networked and provided with (different degrees of) intelligence, in order to interoperate and cooperate in a smart way
- agents are the most natural way of approaching IoT systems featuring complexity, dynamism, situatedness, and autonomy
[Kato et al., 2015, Manzalini and Zambonelli, 2006, Spanoudakis and Moraitis, 2015]
- agents are the most viable abstraction to encapsulate fundamental features such as *control*, *goals*, *mobility*, and *intelligence*, in the development of proactive, cooperating, and context-aware smart objects [Fortino et al., 2012]
- agent-oriented models and technologies are gaining momentum for embedding *decentralised intelligence* [Jamont and Occello, 2016]

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Knowledge-Intensive Environments (KIE)

Information galore

- ubiquitous *knowledge sources* growing in number and size
- *knowledge prosumers* in socio-technical systems (STS) [Whitworth, 2006]
- application *goals* more and more *depending on information* available in the environment [Mariani and Omicini, 2013]



Pervasive Intelligence

Intelligence everywhere

- computation is everywhere around us
- software components are required to **behave intelligently**, understanding their own goals and the context where they have to work
- integration of software components is supposed to add **social intelligence**, possibly through coordination [Castelfranchi, 1998]
- pervasive computing nowadays calls for *ubiquitous intelligence*



Internet of Intelligent Things (IoT)

Intelligent objects in the IoT

- our everyday physical objects should be able to network in the Internet of Things (IoT) [Gubbi et al., 2013, Atzori et al., 2010, Fortino et al., 2014]
- they are required to understand each other, to learn, to understand situations, to understand us [Lippi et al., 2017]
- our *everyday object* should be(come) **intelligent** in the *Internet of Intelligent Things (IoT)* [Arsénio et al., 2014]

Next in Line...

- 1 Scenarios
- 2 Machine Intelligence**
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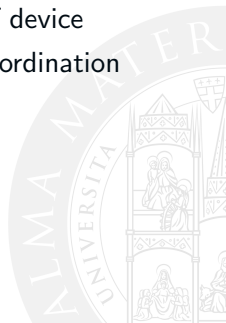
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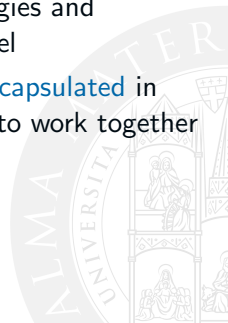
Which Intelligence for the IoT?

- we need *small chunks of machine intelligence*
- spread all over the system
- capable to enable individual intelligence of any sort of device
- promoting *smart* interoperation, collaboration, and coordination among different entities



Vision

- the micro-intelligence vision promote **ubiquitous distribution of intelligence** in large pervasive systems [Calegari, 2018]—such as IoT ones [Calegari et al., 2018a]
- in particular when coupled with agent-based technologies and methods, at both the individual and the collective level
- the idea behind micro-intelligence is that it can be **encapsulated** in devices of any sort, making them smart, and capable to work together in groups, aggregates, societies



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Socio-technical Systems & Requirements I

Socio-technical systems (STS) [Whitworth, 2006]

- artificial systems where both *humans* and *artificial* components play the role of system components
 - from online reservation systems to social networks
- most of nowadays systems are just STS
 - or, at least, cannot be engineering and successfully put to work without a proper socio-technical perspective in the engineering stage



Socio-technical Systems & Requirements II

Socio-technical requirements

- some system requirements are not just merely *technical*
- they concern the way in which humans *perceive* them, *participate* them, *understand* them, include and exploit them into they own processes, including cognitive ones—not just use them
- these are what we call here **socio-technical requirements**
- even though, of course, they *do* have (strong) technical counterparts

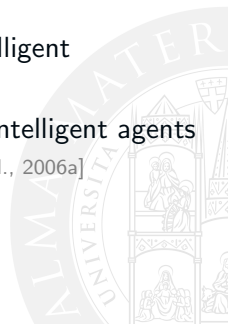


Observability

- *observability* is essential for understanding execution of distributed systems [Tanenbaum and van Steen, 2007]—as in the case of stateless communication in REST
 - *mutual observation* is a pre-condition for many forms of cognitive agent coordination—e.g., behavioural implicit communication (BIC) [Castelfranchi et al., 2010]
 - *inspectability* an essential feature for *online engineering* [Fredriksson and Gustavsson, 2004]—in particular for *artefacts* in MAS environment [Omicini et al., 2008]
- ! observability has a classical, straightforward technical acceptance
- a more articulated socio-technical interpretation is essential for STS
- e.g. making the portion of a system required for effective human interaction *readable* for humans at run time

Malleability

- the ability of changing / adapting at run time is a pre-condition for most forms of self-adaptive / self-organising systems [Omicini et al., 2008]
- e.g. **malleability** of coordination artefacts allows for self-organisation patterns in MAS [Viroli et al., 2005]
- e.g. malleability of a Prolog engine allow for adaptive intelligent middleware [Piancastelli et al., 2008]
- ! malleability may in principle allow both humans and intelligent agents to affect the system behaviour at run time [Omicini et al., 2006a]



Explainability

We need explanations

- it is not enough for STS to just work
- we need to understand them—otherwise, technology is not much different from magic
- e.g. decision support systems need not just to propose solutions, but also to *motivate* them
- e.g. the problem with deep learning till now
- e.g. engineering systems with self-organisation techniques mandates some for of system *predictability*
 - ! as a socio-technical requirement, explanation needs to be understandable by humans

Predictability

We need to be sure

- it is not enough for systems to work
 - we need to know how they will behave—otherwise, it could be dangerous, or, unacceptable, or, ...
- e.g. we like to add features of *self-organising systems* to our systems—but, we need to foresee their evolution over time, at least in general terms
- e.g. complex systems are generally *unpredictable*, however we would need at least partial predictability of their behaviour when we engineer them
- ! as a socio-technical requirement, predictability mandates at least for a general expression of macro-level effects that could be appreciated by a human

Accountability

Systems & norms

- if computational systems are pervasive, and affect every aspects of our everyday life, they are subject of all the *norms* ruling human individual and social behaviour
- *norm compliance* should be enforced by computational systems, starting from the earliest phases of software engineering
- *normative reasoning* should become part of the intelligent behaviour of components and systems
- **accountability**, traceability, and responsibility should be part of each component and every system
- humans need someone to *blame* for anything

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Symbolic vs. Non-symbolic Approaches to AI

- symbolic vs. non-symbolic is a *leitmotiv* in AI research since Brooks' robotics [Brooks, 1991b, Brooks, 1991a]
- many novel approaches to machine intelligence nowadays are increasingly focussing on *non-symbolic* approaches
 - such as deep learning with neural neural networks—e.g., AlphaGo [Silver et al., 2016]
- and how to make them work on the large scale



Back to Symbolic AI?

- non-symbolic approaches have the potential minimise the engineering efforts towards large-scale intelligence
 - yet, we do also need that our large-scale intelligent systems exhibit *socio-technical features* such as *observability*, *explainability*, and *accountability*
 - to make *ubiquitous intelligence* actually work in human organisations and societies
- more classic AI approaches to intelligence can be of help
- such as *agents* and *multi-agent systems* (MAS)
 - as well as *declarative* and *logic-based* approaches



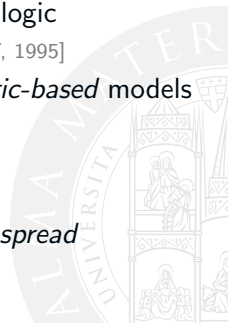
Agents

Agents & multi-agent systems (MAS)

- **agents** are the most viable abstraction to encapsulate fundamental features such as *control*, *goals*, *mobility*, *intelligence* [Zambonelli and Omicini, 2004]
- **MAS** abstractions such as *society* and *environment* [Omicini, 2001] are essential to cope with the complexity of nowadays application scenarios [Omicini and Mariani, 2013]
- agent-oriented models and technologies are gaining momentum for embedding **decentralised intelligence** [Singh and Chopra, 2017] and to *distribute* intelligence in complex systems of any sort [Fortino et al., 2012]

Logic-based Approaches

- declarative and logic-based technologies quite straightforwardly address issues such as *observability* and *explainability*
- in particular when exploiting their inferential capabilities—e.g., [Idelberger et al., 2016]
- logic-based approaches already have a well-understood role in building intelligent agents [Omicini and Zambonelli, 2004]—e.g., the logic [Rao and Georgeff, 1998] behind BDI agents [Rao and Georgeff, 1995]
- instead, in the following we focus on the role that *logic-based* models and technologies can play when used
 - to rule *agent societies*
 - to engineer *agent environment*
- so, again, to *shape the world* around the agents, and *spread intelligence* around them



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Why Logic Programming for Intelligent Systems? I

General features of Logic Programming (LP)

- computation as deduction
- declarative and procedural interpretation match
- reasoning about what is true rather than about what to do
- logic theories as programs and knowledge bases
- programming with relations and inferences
- non-typed tree structures for uniform data representation
- unification as a non-directional mechanism for message passing
- single-assignment variables, step-by-step refinement
- reasoning with incomplete information
- non determinism
- interactive computational model
- ...

Why Logic Programming for Intelligent Systems? II

Overall

LP languages and technologies
represent in principle the most natural candidates for
injecting intelligence
within computational systems



Why Logic Programming for Distributed Systems? I

Early days

- since the early days of logic programming, features like
 - high-level languages
 - non-determinism
 - referential transparency

made the potential for exploitation of parallelism in the execution of logic programs clearly emerge [Gupta et al., 2001]

- at the same time, the articulation of logic computation, with the frequent occurrence of
 - heavy computational load
 - non-trivial computational structures

made the computational techniques developed for logic languages relevant for the general scenario of concurrent / parallel computation

Why Logic Programming for Distributed Systems? II

Or- & and-parallelism

- logic languages like Prolog allow for parallel evaluation
 - the proof tree could be explored parallel / concurrently
 - even more, the potential computational complexity of the proof tree actually *encourages* parallel exploration
- basically, Prolog supports two sorts of parallelism
 - *and-parallelism*
 - *or-parallelism*

fitting **distributed computing**



Logic Programming: Issues I

Why did LP never *really* take off?

- computational costs too high, machinery too huge
- not really suited for programming in the large—intrinsic modularity (predicates) does not really scales up, modules are not enough
- a novel programming paradigm requires huge efforts by programmers
- “no types” makes it difficult (also) to deal with domain-specific applications
- how to deal with non determinism?
- distance from mainstream programming paradigms potentially harms conceptual integrity
- troublesome integration with mainstream technologies
- ...

Logic Programming: Issues II

LP for distributed systems?

- mostly, distributed computing for LP—to share the huge computational load
- distributed computing is *not* the same as distributed systems, at least according to their historical meanings—per se, LP does not work for distributed systems
- interactive computational model works locally—one user querying one engine
- the universal notion of consistency of logic theory does not cope well with the incompleteness and inconsistency intrinsically implied by the needs of distributed pervasive systems
- LP technology does not always integrate well with available tools and technologies for distributed pervasive systems



Ubiquitous Declarative Languages and Technologies

Declarative languages and technologies

- SQL and its derivatives are everywhere in databases and knowledge sources of any sort
- XML and its applications are the de facto standard for the Web as well as for most of the novel application scenarios at any level
- even the shift in object-oriented programming from classes to interfaces in some sense represents a shift towards declarativeness
- declarative models and technologies play an essential roles in agent-oriented computing [Omicini and Zambonelli, 2004]



New LP Technologies

Essential features

- minimal and configurable engines running without heavy computational costs [Denti et al., 2001]
- multi-platform technology, including resource-constrained devices [Denti et al., 2013]
- interoperability with widespread languages, technologies, and standards
- clean model integration for conceptual integrity [Denti et al., 2005]

e.g. tuProlog <http://tuprolog.unibo.it>



Distributing Logic Programs

Concurrent logic processes

- processes represented by logic *processes* in concurrent systems
 - logic *agents* in the acceptance of coordination models [Ciancarini, 1996]
- there, concurrent / distributed systems are first of all collection of logic engines running in a concurrent / distributed way [Robertson, 2004]

e.g. Shared Prolog [Brogi and Ciancarini, 1991], *ACLT* [Denti et al., 1996]

→ moving LP towards *distributed systems* and MAS [Baldoni et al., 2010]

Logic-based Coordination

Logic tuple spaces

- the space of interaction is built around *logic tuple spaces*
[Ciancarini, 1994, Denti et al., 1996]
- allowing for heterogeneous distributed processes to be coordinated
- blackboards and programmable logic tuple spaces promote logic-based coordination of distributed systems

e.g. Shared Prolog [Brogi and Ciancarini, 1991], ReSpecT [Omicini and Denti, 2001]



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Micro-intelligence for the IoT

- IoT scenarios (and CPS as well) mandates for distributed & situated **micro-intelligence**
 - huge numbers of small unit of computation
 - situated within a spatially-distributed environment
 - promoting the local exploitation of high-level symbolic languages
 - with inferential capabilities
- ? what role could the LP models and technologies play in such scenarios?
- ? what LP for the IoT? [Arsénio et al., 2014]



Distributing Intelligence through Logic Engines I

Distributed logic engines

- lightweight and interoperable Prolog engines could be distributed even on resource-constrained devices [Denti et al., 2013]
- *multiple logic theories* are then scattered around, encapsulated in each engine, and associated to individual computational devices and *things* in the IoT
- each logic theory is *situated*, and represents what is true *locally*, according to a simple paraconsistent interpretation
[Blair and Subrahmanian, 1989]
- LP *resolution process* is local to each theory / engine, so it is both standard and consistent [Robinson, 1965]

Distributing Intelligence through Logic Engines II

Our approach: tuProlog

tuProlog <http://tuprolog.unibo.it>

- is a light-weight Prolog system for **distributed** applications and infrastructures [Denti et al., 2001]
- is intentionally designed around a **minimal core**
- can be either statically or dynamically *configured* by loading/unloading **libraries** of predicates
- natively supports **multi-paradigm programming** [Denti et al., 2005], providing a clean, seamless integration model between Prolog and mainstream object-oriented languages
- runs on most known platforms and devices

Making LP Available in Distributed Systems I

- LP promotes *interactive programming*, even though one user / one engine sort
 - in order to meet the needs of nowadays distributed systems, a more *standard* approach should be adopted, in terms of both architecture and technology
 - possibly subsuming standard LP interaction
- e.g. providing logic engines (theories, inference, resolution) *as a service*, so that standard distributed components and applications could exploit them
- exploiting a XaaS (everything as a service) architecture

Making LP Available in Distributed Systems II

Our approach: Logic Programming as a Service (LPaaS)

Logic Programming as a Service (LPaaS) [Calegari et al., 2018c]

- provides an abstract view of an LP inference engine in terms of *service*
- promotes *interoperability*, *encapsulation*, and *situatedness*, as well as *context-awareness*
- each logic engine exposes its *services* concurrently to multiple clients, via two interfaces (*client* and *configurator*)
- preserving the standard resolution process
- providing for both *stateless* and *stateful* client-server interaction
- promoting *time-sensitive* and *space-sensitive* computation

Making LP Available in Distributed Systems III

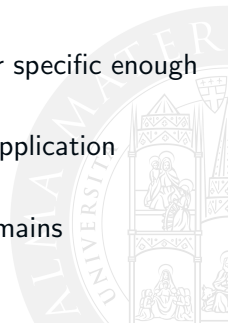
Main ideas

- embedding a **logic theory** in every computational device composing the MAS environment
- along with a working **logic engine** providing basic inferential capabilities
- every local service is *situated* in that it describes what is locally true
- **agents** exploit both **knowledge representation** provided by logic theories and the **inferential capabilities** provided by logic engines as a distributed service
- thus **injecting intelligence in MAS environment**



Dealing with Situatedness & Domain-specific Scenarios I

- pervasive applications typically demands for domain-specific approaches
- multiple, heterogeneous devices in the IoT usually have specific application goals and manage specific sorts of information
- situatedness require reactivity to environment change
- ! LP is general enough to deal with whatever, but never specific enough to do it well
- many specific logics exist to deal with many diverse application scenarios—e.g., S4 modal logic for spatial computing
- LP can be extended to capture different logic and domains



Dealing with Situatedness & Domain-specific Scenarios II

Our example: Labelled Variables in Logic Programming

In Labelled Variables in Logic Programming (LVLP) [Calegari et al., 2018b]

- logic variable can be associated to a *label*
- labels are **domain-specific**
- each logic engine can be configured with its own set of domain-specific label, along with the specific functions to interfere with the logic resolution process, without losing declarativeness
- labels allows for a customisable computational model (domain-specific *labelled system*) bound to the standard LP computation

e.g. a wardrobe could host a LVLP engine whose labelled system represent its content, and helps in dress selection [Calegari et al., 2018b]

Dealing with Situatedness & Domain-specific Scenarios III

LPaaS & LVLP in (M)MAS

- LPaaS can be extended towards domain-specific computations via LVLP
- each LPaaS service can be enriched with its local LVLP domain-specific model



Dealing with Situatedness & Domain-specific Scenarios IV

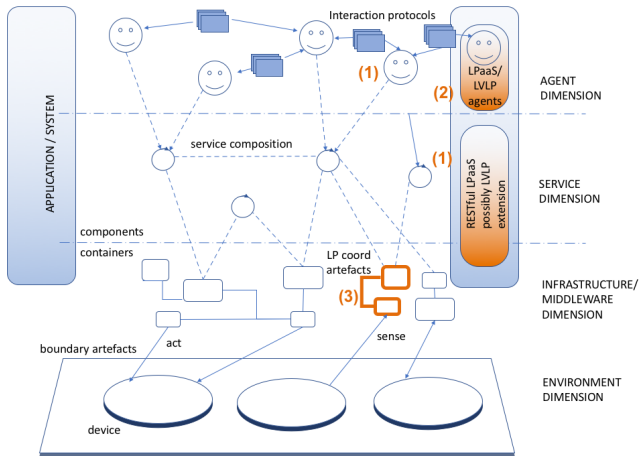


Figure: Overview of a LPaaS-LVLP MAS

Dealing with Situatedness & Domain-specific Scenarios V

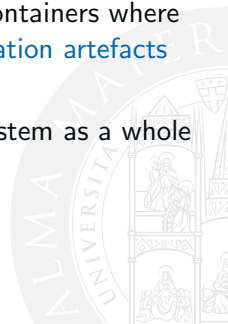
The picture above illustrates the model of the LPaaS-LVLP approach depicting the whole picture where

- 1 some agents are kept more lightweight and rely on infrastructural services (or other more “intelligent” agents) to get LPaaS functionalities
- 2 some agents embed the LPaaS-LVLP functionalities
- 3 some LP functionalities are embedded in some services provided by the middleware (namely by the containers)



Dealing with Situatedness & Domain-specific Scenarios VI

- at the bottom layer, the physical / computational environment lives, with **boundary artefacts** [Omicini et al., 2006a] taking care of its representation and interactions with the rest of the MAS
- then, typically, some middleware infrastructure provides common API and services to application-level software – i.e., the containers where service components live – there including the **coordination artefacts** [Omicini et al., 2004] governing the interaction space
- finally, on top of the middleware, the application / system as a whole lives, viewed as a *mixture of services and agents*



Logic-based Coordination Artefacts I

Social intelligence

- is another dimension that MAS models and technologies can fruitfully exploit
- in particular by building agent societies around *programmable*, *observable* and *malleable* coordination abstractions [Omicini et al., 2006a]



Logic-based Coordination Artefacts II

Coordination models and technologies

- play that role [Ciancarini, 1996] by providing *coordination media* as the basic abstractions around which agent societies can be designed [Ciancarini et al., 2000]
- via agent *coordination middleware*
- typically, a multiplicity of distributed coordination media are made available to the MAS: each group of agents can interact within a shared environment via a locally-deployed coordination medium



Logic-based Coordination Artefacts III

Coordination as a service [Viroli and Omicini, 2006]

- coordination artefacts are provided as services for the agents to participate to *properly-normed* social activities
- autonomous agents submit themselves to the coordination policies embedded in a coordination medium by choosing to interact with other agents through the service provided by the medium itself
- thus constituting an agent society



Logic-based Coordination Artefacts IV

Our approach: TuCSoN coordination middleware

The TuCSoN coordination model [Omicini and Zambonelli, 1999]

- provides MAS with *tuple centres* [Omicini and Denti, 2001] as the coordination media
- extending LINDA tuple spaces [Gelernter, 1985] with *programmability* [Denti et al., 1997]
- based on the ReSpecT [Omicini, 2007] logic-based language, where tuples are *logic tuples*
- TuCSoN middleware supports *multiple* ReSpecT tuple centres, which can be spatially distributed and connected via *linkability* [Omicini et al., 2006b]



Logic-based Coordination Artefacts V

Coordination artefacts [Omicini et al., 2004]

- encapsulate coordination policies for distributed systems
- can inject *social intelligence* within computational systems
[Castelfranchi, 1998]
- can be *observable* and *malleable* [Omicini et al., 2008]

Logic-based coordination artefacts

- represent coordination policies declaratively
- pave the way towards (partial) formalisation of complex systems

Logic-based Coordination Artefacts VI

Our approach: ReSpecT coordination artefacts

ReSpecT coordination artefacts (ReSpecT) [Omicini, 2007]

- are *inspectable* and *malleable*
- can express any Turing-computable coordination policy [Denti et al., 1998]
- there, both *communication* and *coordination* theories are first-order logic theories
- can be used within the TuCSoN middleware for MAS coordination [Omicini and Zambonelli, 1999]



Logic-based Coordination Artefacts VII

ReSpecT tuple centres

- *logic tuples* in the tuple space
- ReSpecT *specification tuples* in the *specification space*
- which sets the coordinative behaviour of the medium by defining the *reaction* of the tuple centres to relevant MAS events



Logic-based Coordination Artefacts VIII

Features

- *programmability* of the coordination medium – along with the Turing-equivalence of ReSpecT [Denti et al., 1998] – makes it possible to embed any computable coordination policy within the coordination media, possibly allowing for *intelligent social behaviour*—e.g., [Omicini et al., 1995]
- *observability* of all tuples in a tuple centre makes it possible to reason about the state and behaviour of the corresponding agent society
- *malleability* of the tuple centre behaviour makes it possible to *change* (possibly intelligent) coordinative behaviours at run-time, paving the way towards *adaptability*

Logic-based Coordination Artefacts IX

Scalability

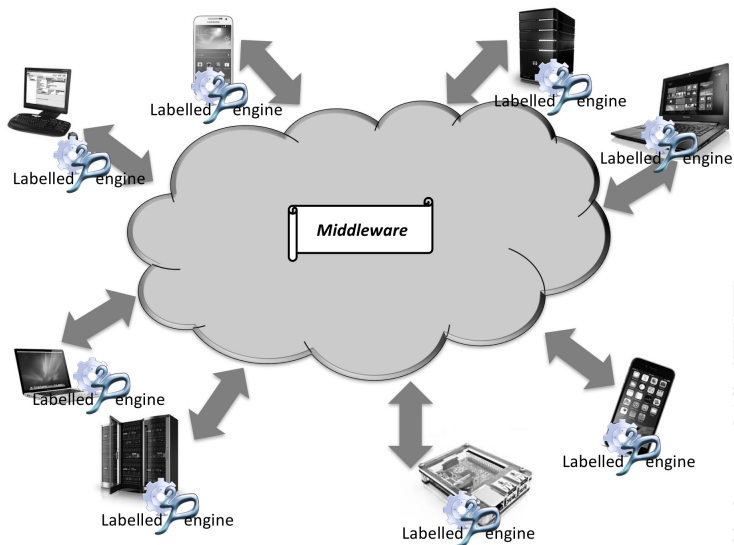
- since ReSpecT tuple centres can be designed to be locally deployed within a physically-distributed environment
 - with a (possibly huge) number of spatial containers and physical devices
 - correspondingly embodying the laws for *local* coordination, ruling the social behaviour of the locally-interacting agents
- any coordination policy can then be tailored to the specific needs of every locality in a large-scale scenario—thus providing a way towards **scalable coordination**



Conclusion I

- when properly integrated within agent-based models and technologies, logic-based approaches have the potential to be exploited for *knowledge representation* and *reasoning* at the *large scale*
- we intentionally ignored the role of logic within agents, focussing instead on how logic-based models can be exploited to inject *micro-intelligence* through agent *societies* and *MAS environment*
- by adopting tuProlog, LPaaS, LVLP, and ReSpecT as our reference logic-based models and technologies, we discussed their potential impact within large-scale MAS for complex application scenarios such as the IoT

Conclusion II



Conclusion III

Altogether, the logic-based approaches discussed in this paper can lead to the overall architecture depicted in the picture above. There,

- distributed logic engines provide for widespread *micro-intelligence*
- exploited as standard *services* by components of any sorts, including intelligent agents via LPaaS
- situated and *domain-specific* extensions via LVLP
- coordinated via ReSpecT logic-based artefacts, encapsulating *social intelligence*
- based on a logic-based *middleware* like TuCSon



Conclusion IV

In the end, whereas non-symbolic approaches to AI are currently taking the stage – especially in the eye of the public opinion – symbolic approaches, yet with a long read ahead of them, may still have the potential to be key players in the future of large-scale intelligent systems



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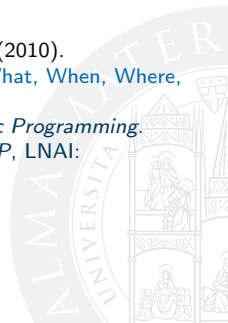
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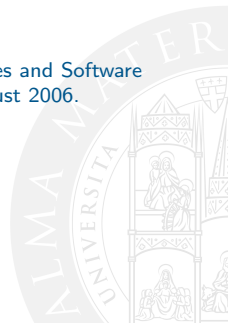
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- On APICe

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- On SlideShare

→ <http://www.slideshare.net/andreaomicini/injecting-microintelligence-in-the-iot-logicbased-approaches-for-mmas>

Injecting (Micro)Intelligence in the IoT: Logic-based Approaches for (M)MAS

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Invited Talk @ *International Workshop
on Massively Multi-Agent Systems (MMAS 2018)*
Stockholm, Sweden, 14 July 2018

